Note on the DDK filters:

In Kusche et al. 2009, only the DDK1 - DDK3 are explicitly listed with the given parameters (see Table 1 from Kusche et al. 2009).

Table 1	Smoothing	characteristics	of the three	decorrelation	filters used in this study
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Decorrelation filter	Corresponding Gaussian radius (km)	Parameter <i>a</i> and <i>p</i>	
	Acc. to Kusche (2007, tables 1+2)	Acc. to $\omega_l = \frac{1}{2}$	Acc. to Kusche (2007)
DDK1	1,350	530	$a = 1 \times 10^{14}, p = 4$
DDK2	900	340	$a = 1 \times 10^{13}, p = 4$
DDK3	660	240	$a = 1 \times 10^{12}, p = 4$

The parameter *a* is a weighting factor. By *p* we denote the exponential parameter in a power law of the type l^{-p} , fitted to the empirical signal degree variance [for details, cf. Kusche 2007, Eqs. (47) and (48)]

For DDK4 and higher, ICGEM uses the scale factors and powers as indicated below. For more explanation and experimental DDKs, users can refer to <u>https://github.com/strawpants/GRACE-filter</u>.

Filter	Scale	Power
DDK8	5 x 10 ⁹	4
DDK7	1 x 10 ¹⁰	4
DDK6	5 x 10 ¹⁰	4
DDK5	1 x 10 ¹¹	4
DDK4	5 x 10 ¹¹	4
DDK3	1 x 10 ¹²	4
DDK2	1 x 10 ¹³	4
DDK1	1 x 10 ¹⁴	4

Reference:

Kusche, J., Schmidt, R., Petrovic, S., Rietbroek, R. Decorrelated GRACE time-variable gravity solutions by GFZ, and their validation using a hydrological model. *J Geod* **83**, 903–913 (2009). https://doi.org/10.1007/s00190-009-0308-3